

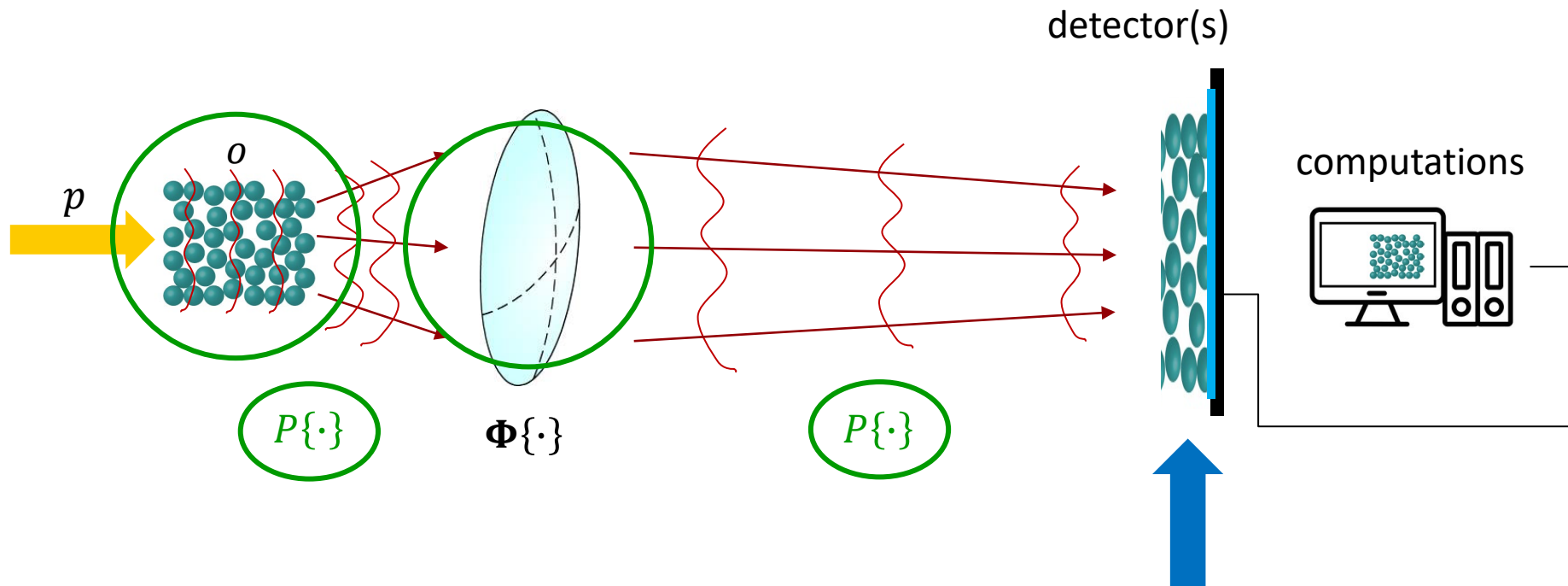


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Associate Professor :: École Polytechnique Fédérale de Lausanne

Chapter 3 – Detector sampling and DFT

Lenses and imaging

A more detailed model



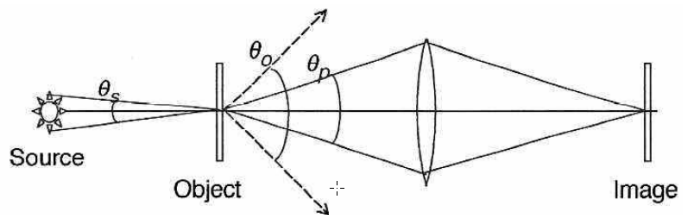
Recap on imaging

Coherent vs incoherent imaging

Coherent

$$I_i(u, v) = \left| \iint U_g(\xi, \eta) h(u - \xi, v - \eta) d\xi d\eta \right|^2$$

$$U_i(x, y) = \mathcal{F}^{-1} \left\{ \mathcal{F} \{ U_g(x, y) \} P(-\lambda z_i f_x, -\lambda z_i f_y) \right\}$$



Coherent if $\theta_s \ll \theta_p$

Incoherent if $\theta_s \geq \theta_o + \theta_p$

Partially coherent in-between

Incoherent

$$I_i(u, v) = \kappa \iint I_g(\xi, \eta) |h(u - \xi, v - \eta)|^2 d\xi d\eta$$

$$I_i(u, v) = \kappa \mathcal{F}^{-1} \left\{ \mathcal{F} \{ I_g(\xi, \eta) \} OTF(f_x, f_y) \right\}$$

$$OTF(f_x, f_y) = P(-\lambda z_i f_x, -\lambda z_i f_y) \star P(-\lambda z_i f_x, -\lambda z_i f_y)$$

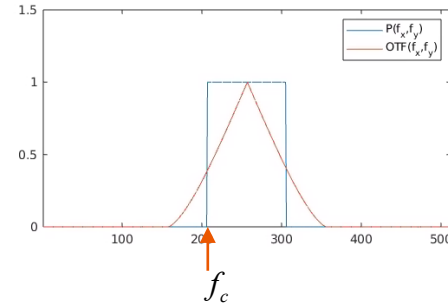
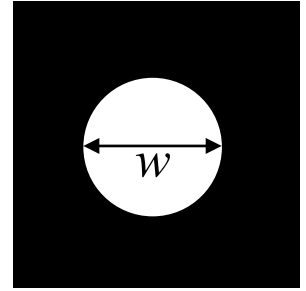
Circular pupil

Exit / entrance pupil diameter w_i

$$P(x, y) = \text{circ}\left(\frac{r}{w_i/2}\right)$$

$$H(f_x, f_y) = \text{circ}\left(\frac{\lambda z_i f_r}{w_i/2}\right)$$

$$f_c = \frac{1}{2} \frac{w_i}{\lambda z_i} \quad \text{Coherent cutoff frequency}$$



Circular pupil

Exit / entrance pupil diameter w_i

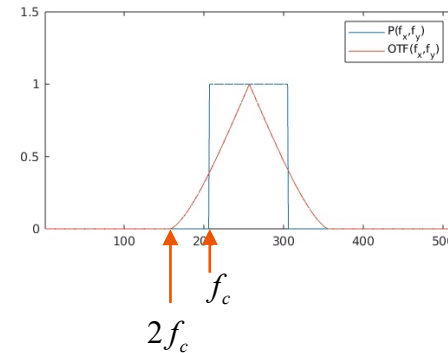
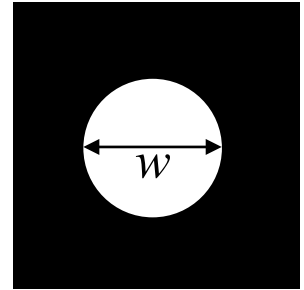
$$P(x, y) = \text{circ}\left(\frac{r}{w_i/2}\right)$$

$$H(f_x, f_y) = \text{circ}\left(\frac{\lambda z_i f_r}{w_i/2}\right)$$

$$OTF(f_x, f_y) = H(f_x, f_y) \star H(f_x, f_y)$$

$$f_c = \frac{1}{2} \frac{w_i}{\lambda z_i} \quad \text{Coherent cutoff frequency}$$

$$f_i = \frac{w_i}{\lambda z_i} \quad \text{Incoherent cutoff frequency}$$



Circular pupil – non paraxial

Pupil diameter w

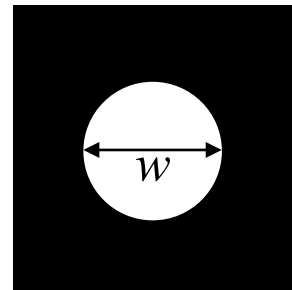
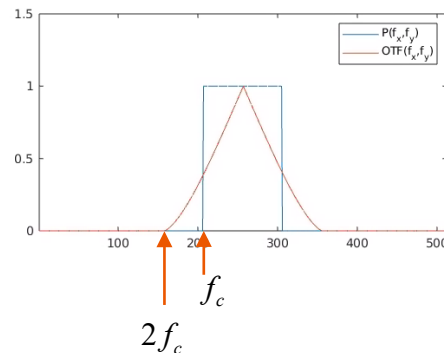
$$P(x, y) = \text{circ}\left(\frac{r}{w_i/2}\right)$$

$$f_c = \left(\frac{w_i}{2z_i}\right) \frac{1}{\lambda} = \frac{\text{NA}}{\lambda}$$

Coherent cutoff frequency

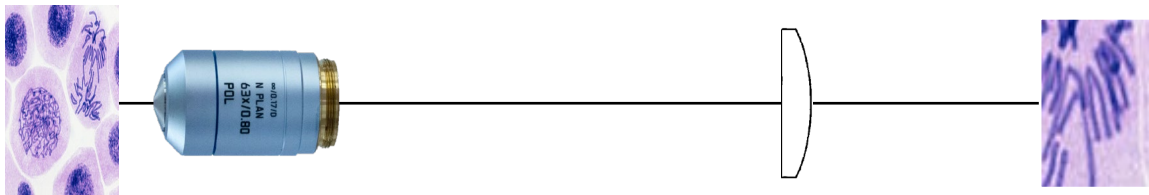
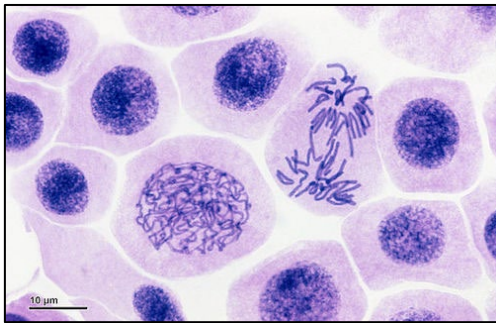
$$f_i = \frac{w_i}{\lambda z_i} f_c = \left(\frac{w_i}{2z_i}\right) \frac{2}{\lambda} = \frac{2\text{NA}}{\lambda}$$

Incoherent cutoff frequency



An optical microscope

What NA do I need to resolve these DNA strains?



How small should my pixel size be to ensure no info is lost?

2x4=8
5x6=30

Course contents



**Cover the unifying concepts of imaging, including with electrons, optics, X-rays.
In 2D, 3D, and beyond.**

Chapter 3 – Detector, sampling, and DFT

- The Whittaker-Shannon sampling theorem
- Nyquist sampling
- Aliasing
- Discrete Fourier transform (DFT)

The Whittaker-Shannon sampling theorem

The Whittaker-Shannon sampling theorem



Sampling → Very general analog to digital transformation

- Sampling for sound
- Measuring images with pixelated cameras
- Measuring any type of intensities with detectors
- Simulating masks
- Simulation of propagation

The Whittaker-Shannon sampling theorem

Intensity of the field is measured by the detector

$$g(x, y) = |\psi(x, y)|^2$$

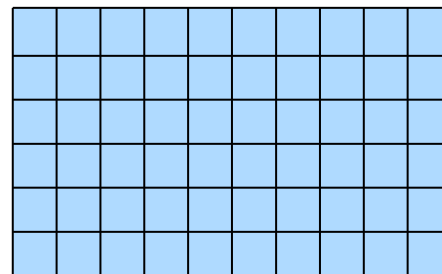
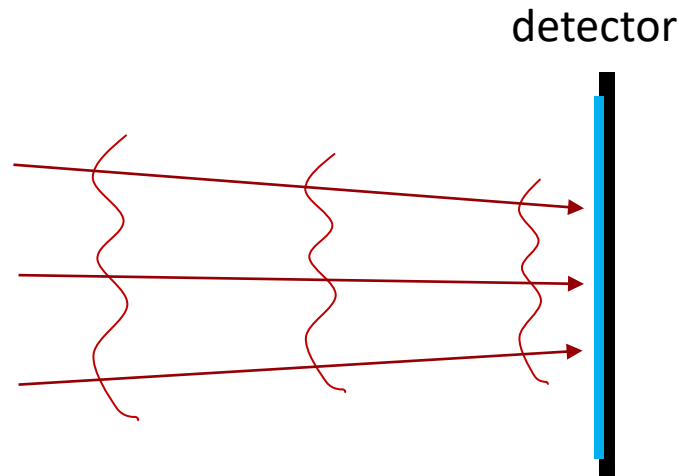
- Image
- Propagated wave

Assuming a detector with perfectly sharp response

$$g_{m,n} = g(m\Delta x, n\Delta y)$$

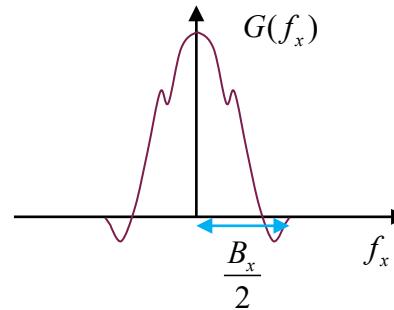
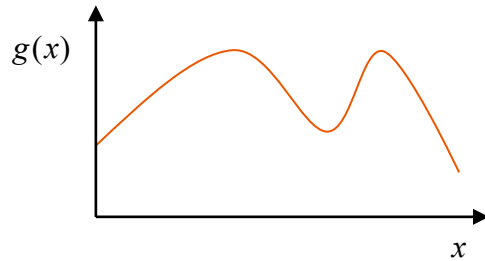
$\Delta x, \Delta y$ Pixel periods (pixel separation)

m, n Integer indices



Band-limited function

$$\mathcal{F}\{g(x)\} = G(f_x)$$



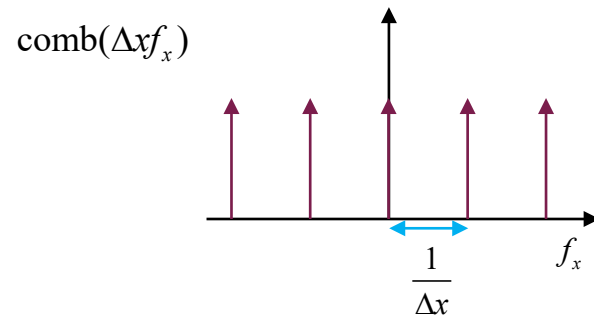
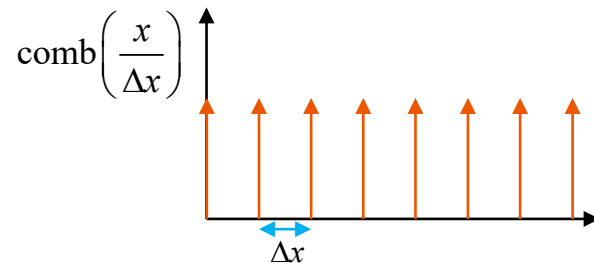
Not that the full bandwidth of the signal

$$B_x = 2f_{max}$$

comb function

$$\text{comb}\left(\frac{x}{\Delta x}\right) = \sum_{m=-\infty}^{\infty} \delta\left(\frac{x}{\Delta x} - m\right) = \Delta x \sum_{m=-\infty}^{\infty} \delta(x - m\Delta x)$$

$$\mathcal{F}\left\{\text{comb}\left(\frac{x}{\Delta x}\right)\right\} = \Delta x \text{comb}(\Delta x f_x)$$

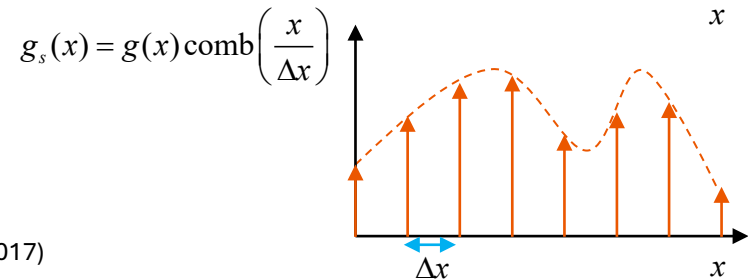
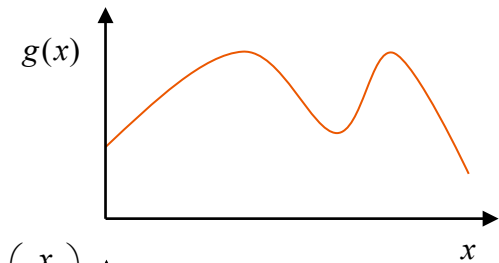
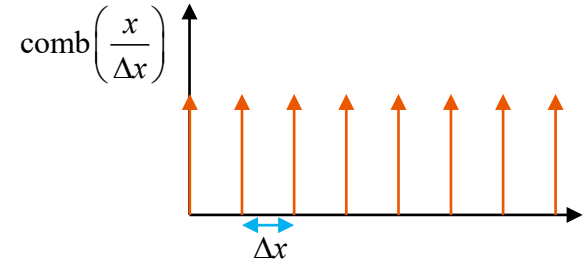


The Whittaker-Shannon sampling theorem

$$\text{comb}\left(\frac{x}{\Delta x}\right) = \sum_{m=-\infty}^{\infty} \delta\left(\frac{x}{\Delta x} - m\right) = \Delta x \sum_{m=-\infty}^{\infty} \delta(x - m\Delta x)$$

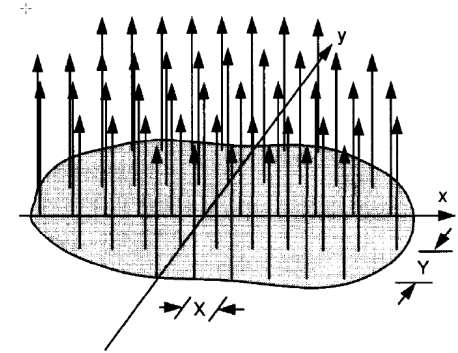
Sampled function in continuous space

$$g_s(x) = g(x) \text{comb}\left(\frac{x}{\Delta x}\right) = \sum_{m=-\infty}^{\infty} g(m\Delta x) \delta\left(\frac{x}{\Delta x} - m\right)$$



The Whittaker-Shannon sampling theorem

$$\text{comb}\left(\frac{x}{\Delta x}\right)\text{comb}\left(\frac{y}{\Delta y}\right) = \sum_{m=-\infty}^{\infty} \sum_{n=-\infty}^{\infty} \delta\left(\frac{x}{\Delta x} - m, \frac{y}{\Delta y} - n\right)$$



Sampled function in continuous space

$$g_s(x, y) = g(x, y) \text{comb}\left(\frac{x}{\Delta x}\right) \text{comb}\left(\frac{y}{\Delta y}\right) = \sum_{m=-\infty}^{\infty} g(m\Delta x, n\Delta y) \delta(x - m\Delta x, y - n\Delta y)$$

The Whittaker-Shannon sampling theorem

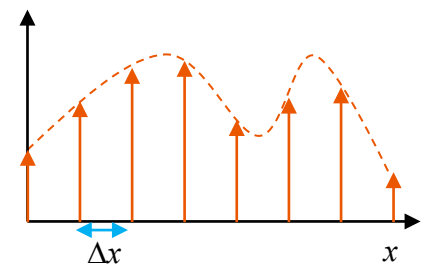
$$g_s(x, y) = g(x, y) \operatorname{comb}\left(\frac{x}{\Delta x}\right) \operatorname{comb}\left(\frac{y}{\Delta y}\right)$$

$$G_s(f_x, f_y) = G(f_x, f_y) * \left[\Delta x \Delta y \operatorname{comb}(\Delta x f_x) \operatorname{comb}(\Delta y f_y) \right]$$

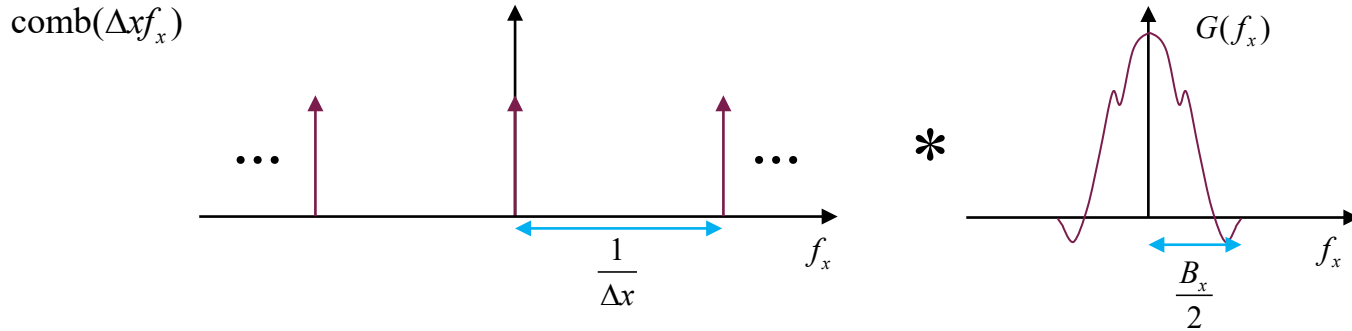
$$G_s(f_x, f_y) = G(f_x, f_y) * \left[\sum_{p=-\infty}^{\infty} \sum_{q=-\infty}^{\infty} \delta\left(f_x - \frac{p}{\Delta x}, f_y - \frac{q}{\Delta y}\right) \right]$$

$$G_s(f_x, f_y) = \sum_{p=-\infty}^{\infty} \sum_{q=-\infty}^{\infty} G\left(f_x - \frac{p}{\Delta x}, f_y - \frac{q}{\Delta y}\right)$$

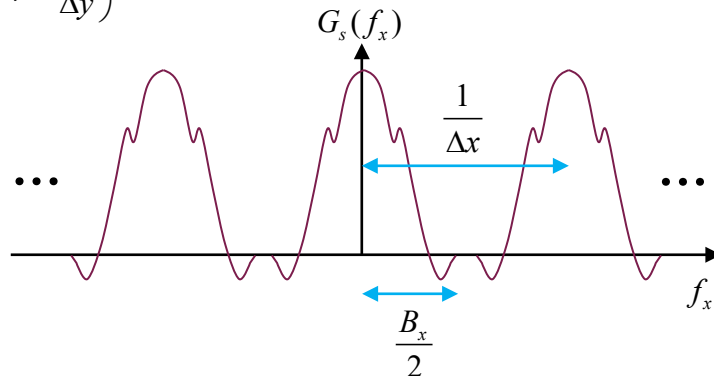
$$g_s(x) = g(x) \operatorname{comb}\left(\frac{x}{\Delta x}\right)$$



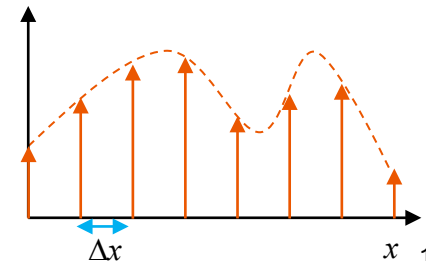
The Whittaker-Shannon sampling theorem



$$G_s(f_x, f_y) = \sum_{p=-\infty}^{\infty} \sum_{q=-\infty}^{\infty} G\left(f_x - \frac{p}{\Delta x}, f_y - \frac{q}{\Delta y}\right)$$

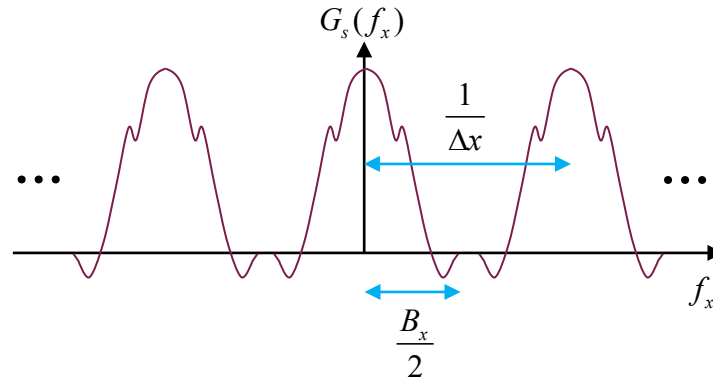


$$g_s(x) = g(x) \text{comb}\left(\frac{x}{\Delta x}\right)$$

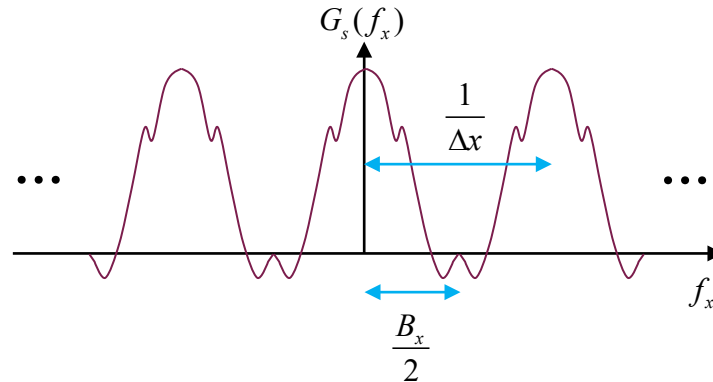


Nyquist sampling

Oversampled $\Delta x < \frac{1}{B_x}$



Nyquist sampled $\Delta x = \frac{1}{B_x} = \frac{1}{2f_{max}}$



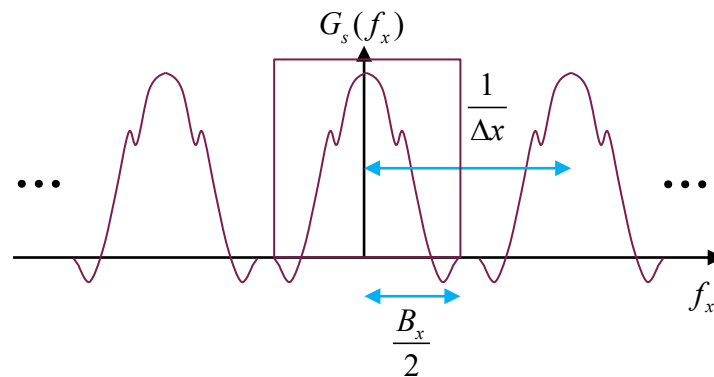
Recovering the initial signal

$$G(f_x, f_y) = G_s(f_x, f_y) \operatorname{rect}\left(\frac{f_x}{B_x}\right) \operatorname{rect}\left(\frac{f_y}{B_y}\right)$$

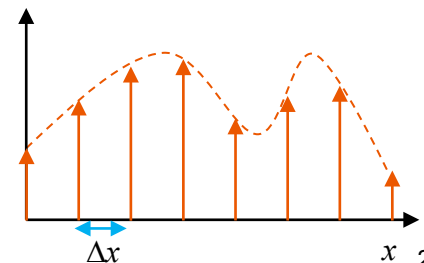
$$g(x, y) = g_s(x, y) * [B_x B_y \operatorname{sinc}(B_x x) \operatorname{sinc}(B_y y)]$$

$$g(x, y) = \left[\Delta x \Delta y \sum_{m=-\infty}^{\infty} \sum_{n=-\infty}^{\infty} g(m\Delta x, n\Delta y) \delta(x - m\Delta x, y - n\Delta y) \right] * [B_x B_y \operatorname{sinc}(B_x x) \operatorname{sinc}(B_y y)]$$

$$g(x, y) = \Delta x \Delta y B_x B_y \sum_{m=-\infty}^{\infty} \sum_{n=-\infty}^{\infty} g(m\Delta x, n\Delta y) \operatorname{sinc}(B_x [x - m\Delta x]) \operatorname{sinc}(B_y [y - n\Delta y])$$



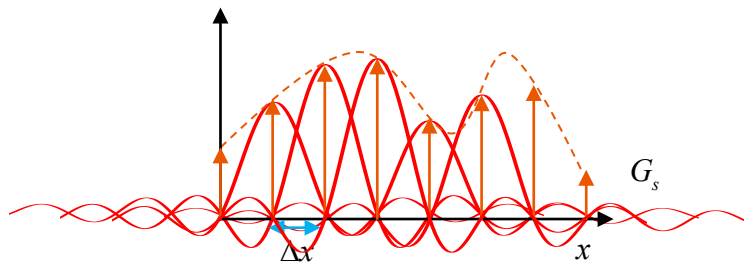
$$g_s(x) = g(x) \operatorname{comb}\left(\frac{x}{\Delta x}\right)$$



Recovering the initial signal

Sinc interpolation \rightarrow Band-limited signals

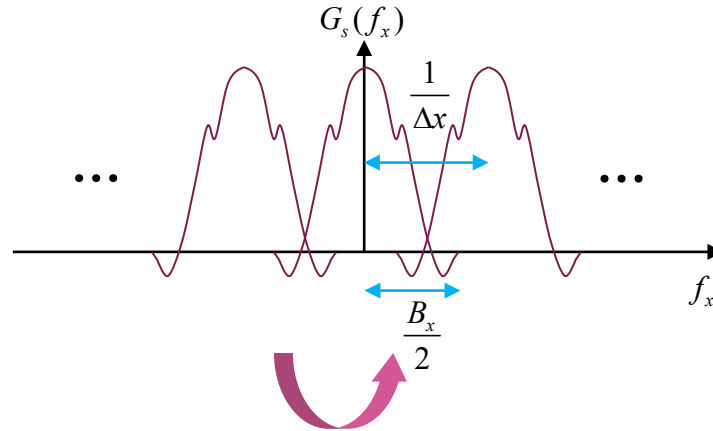
$$g(x, y) = \Delta x \Delta y B_x B_y \sum_{m=-\infty}^{\infty} \sum_{n=-\infty}^{\infty} g(m\Delta x, n\Delta y) \text{sinc}(B_x [x - m\Delta x]) \text{sinc}(B_y [y - n\Delta y])$$



Aliasing

Undersampled

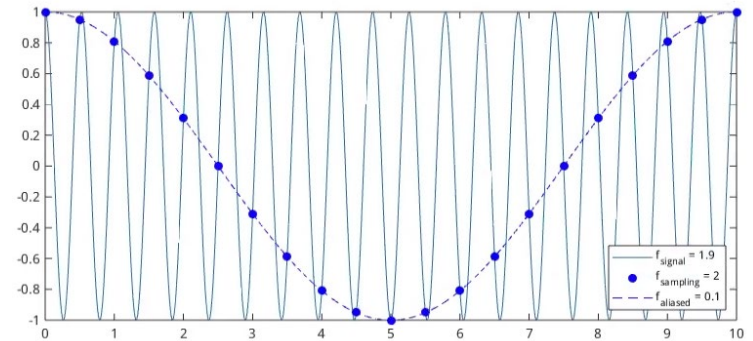
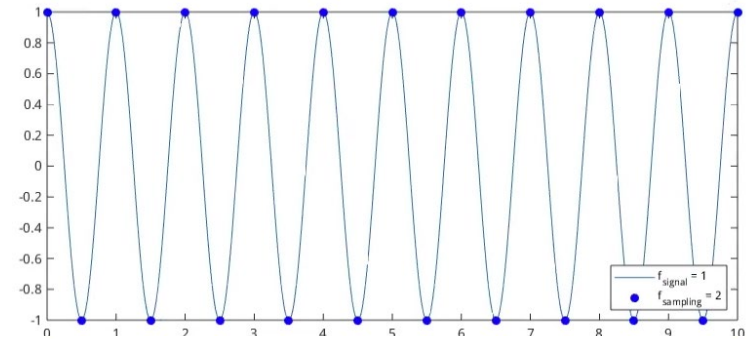
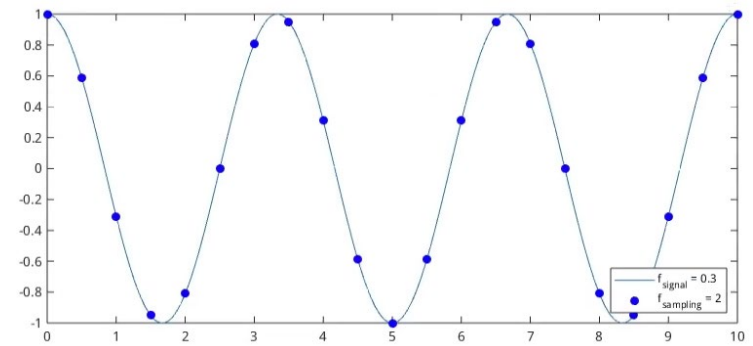
$$\Delta x > \frac{1}{B_x}$$



Large spatial frequencies start to “look like” smaller spatial frequencies

[aliasing.m](#)

Aliasing



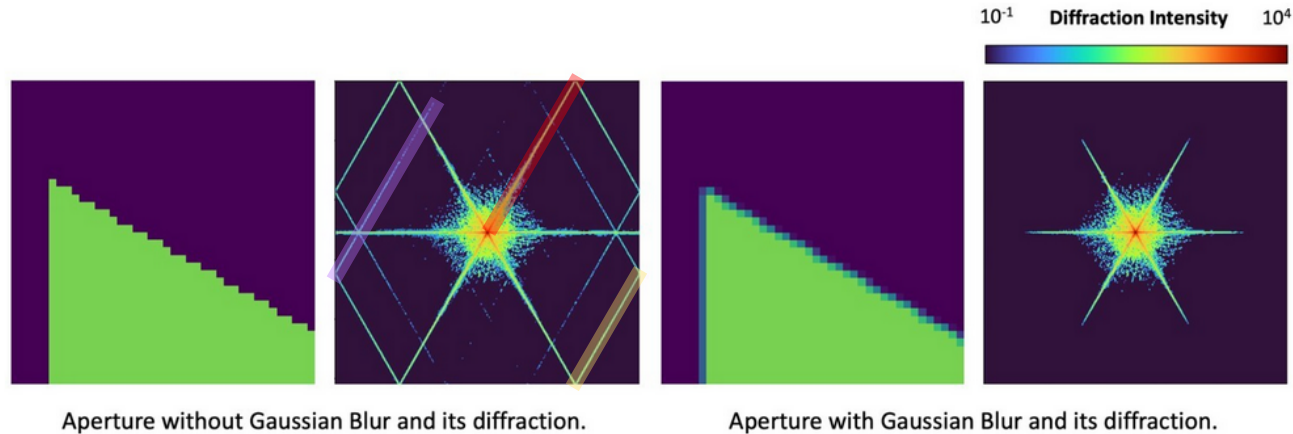
aliasing.m

Aliasing in 2D

Edge smoothing is important when simulating pinholes or apertures

Figure 4 of 6

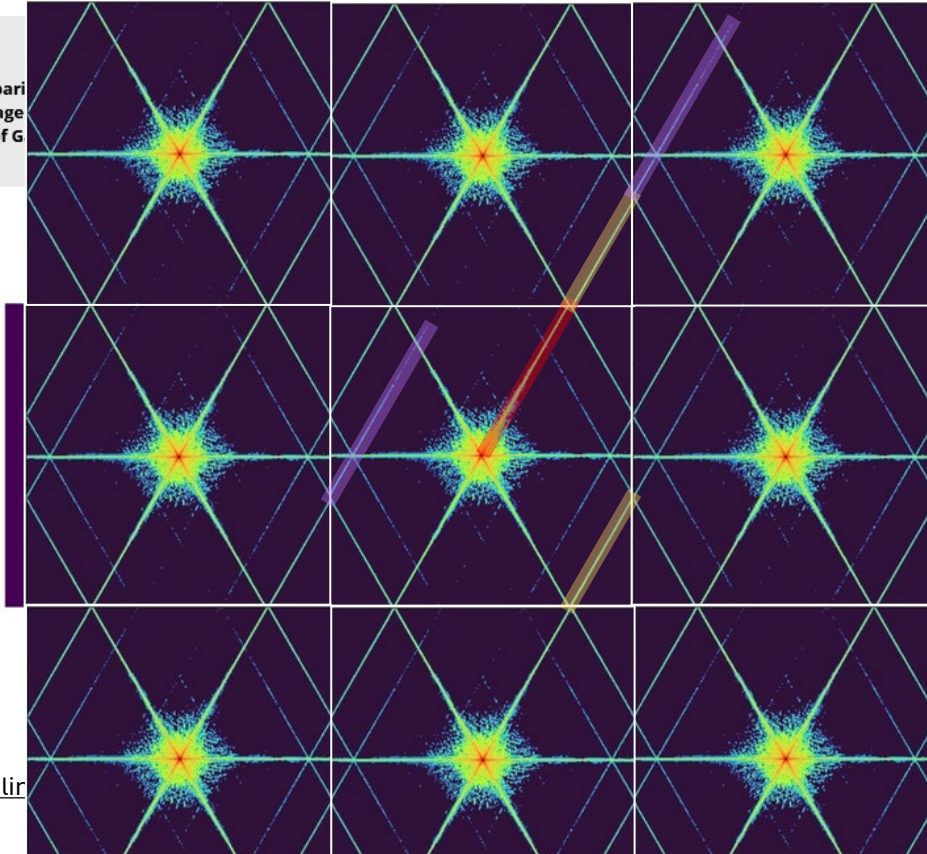
Figure 3. Comparison of Gaussian function effect between two diffraction images. Both diffraction images used the same setting for particle and aperture conditions. The diffraction image produced by the specimen without Gaussian blur shows many noise artifacts compared to the opposite. The aperture image was zoomed in for better visualisation of Gaussian blur effect.



Aliasing in 2D

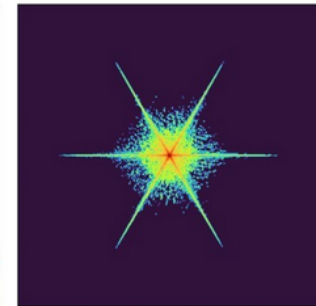
a

Figure 4 of 6
Figure 3. Compari
diffraction image
visualisation of G



ing for particle and aperture conditions. The
e aperture image was zoomed in for better

10^{-1} Diffraction Intensity 10^4



ian Blur and its diffraction.

Aliasing in 2D



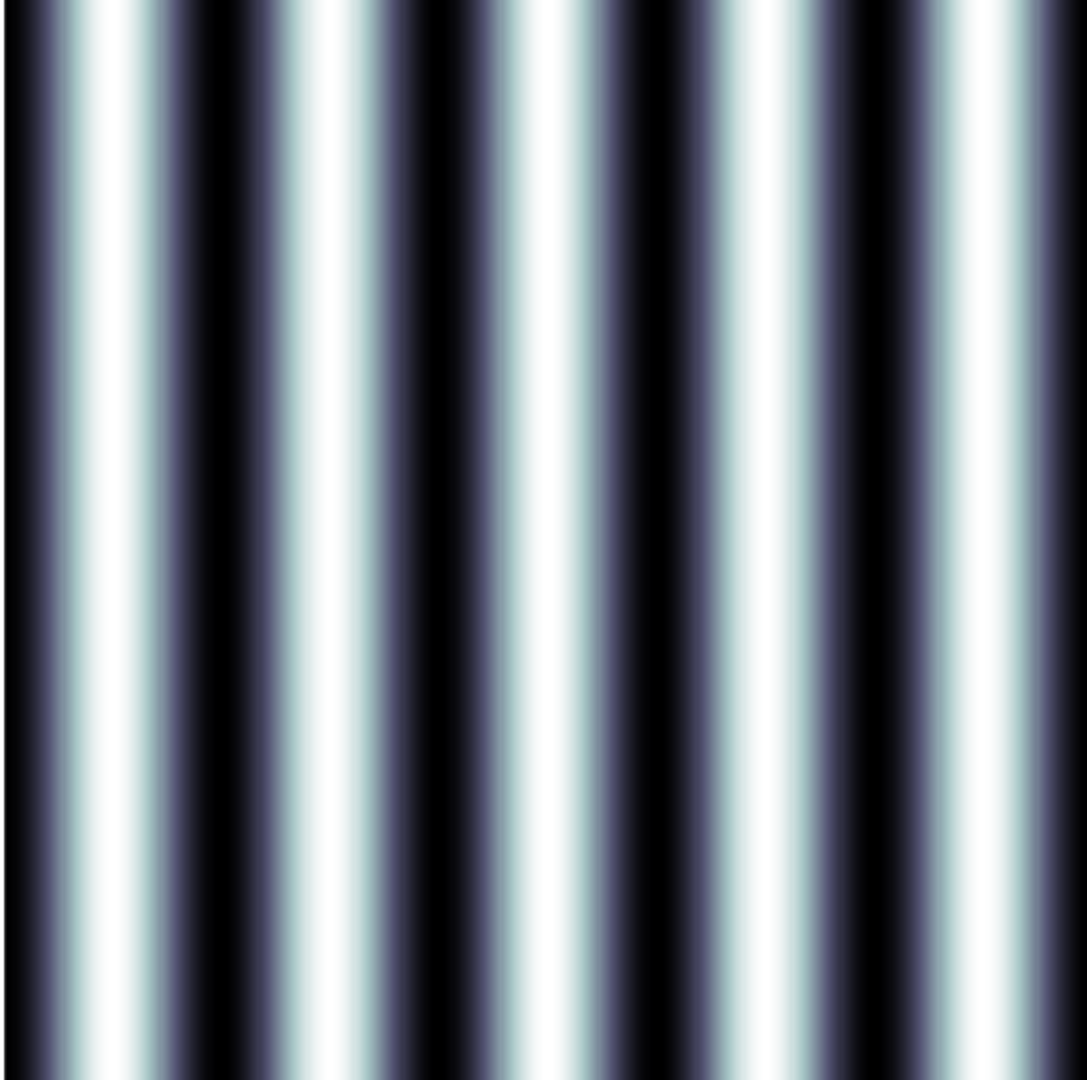
Subtle effect to notice by eye

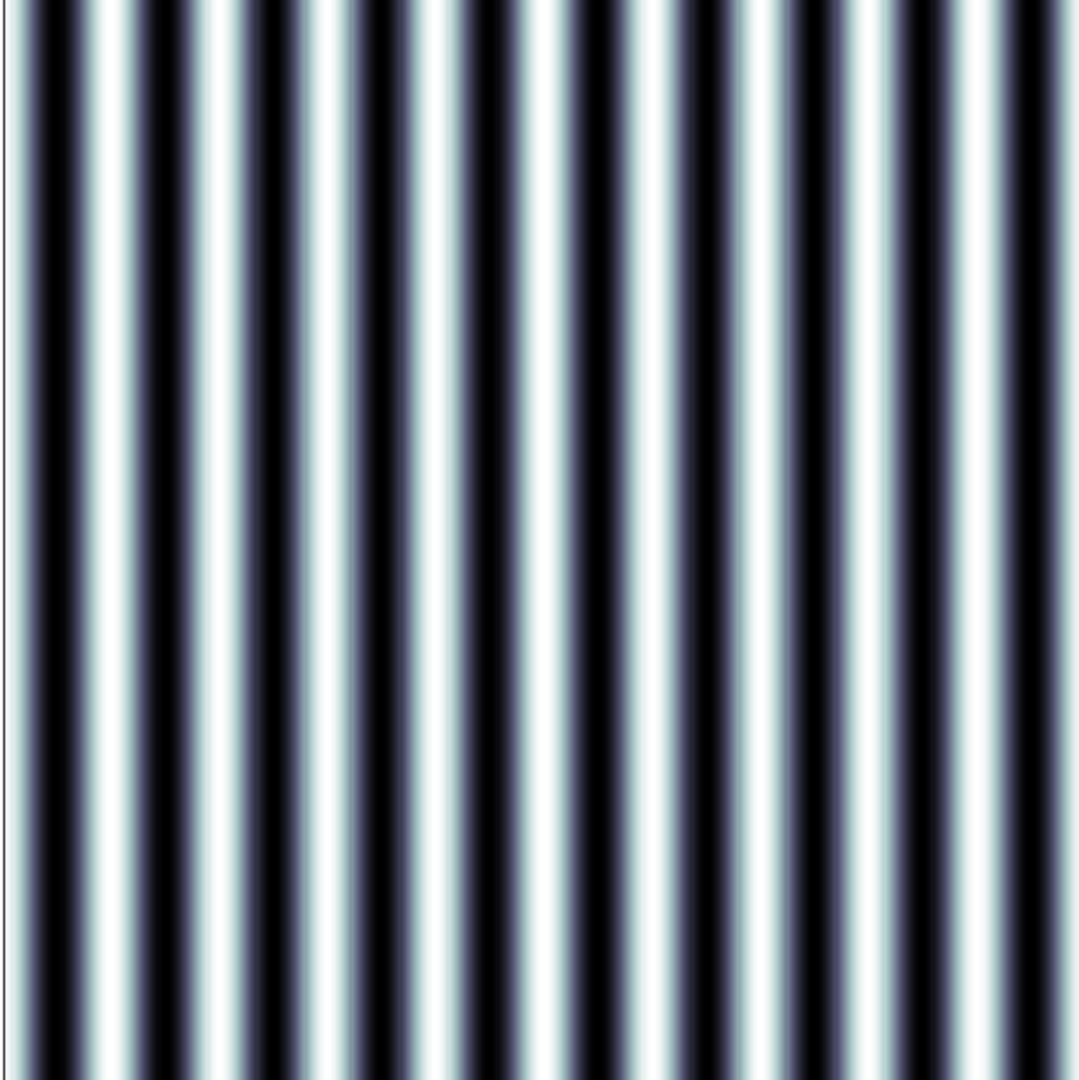
One case where it is noticeable is if you have a periodic patterns

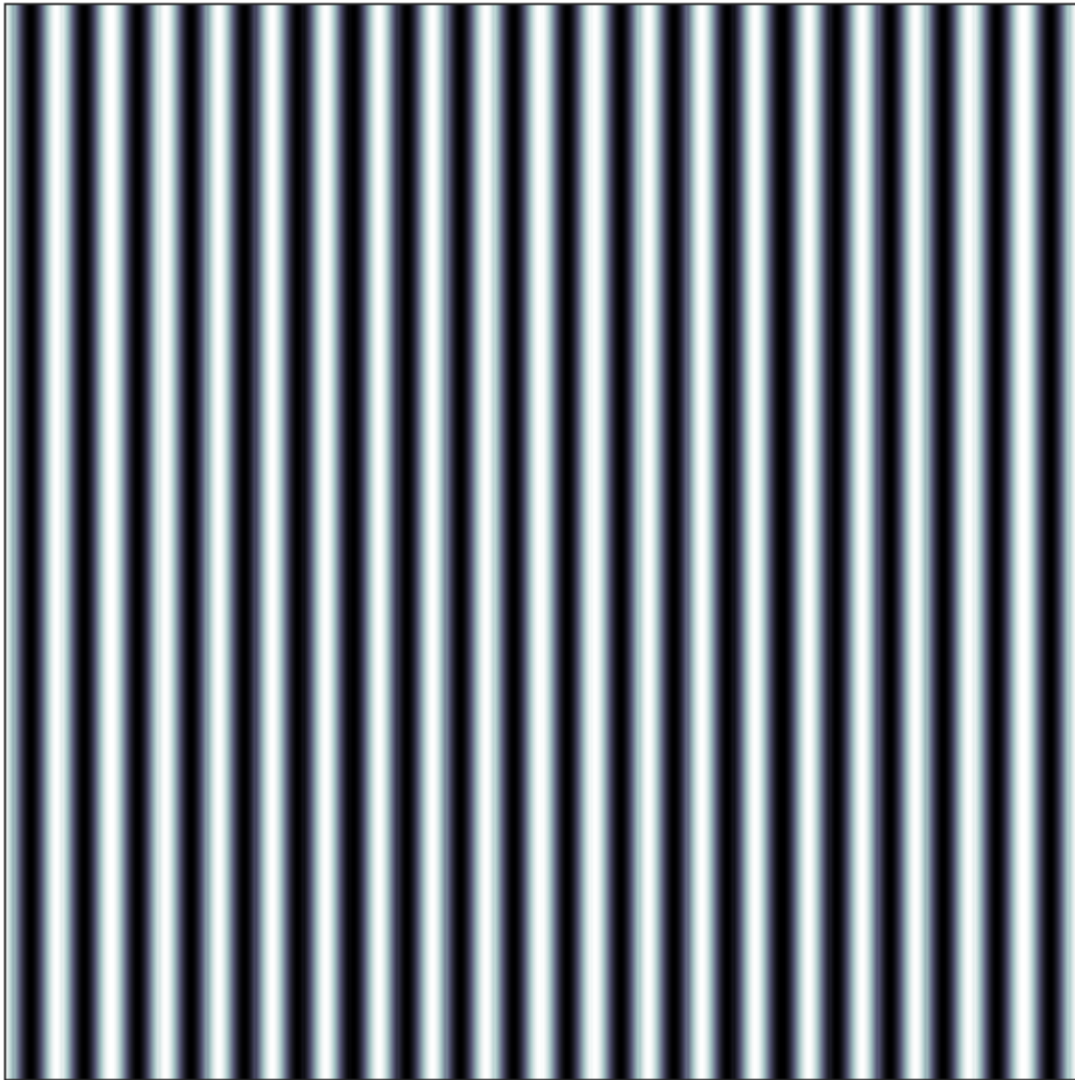


Image from <https://graphicdesign.stackexchange.com/questions/125041/how-to-approach-cleaning-up-an-emergent-moire-pattern-in-a-low-resolution-image>

<https://play.google.com/store/apps/details?id=net.rahorton.fft&hl=en>













Sampling for an imaging system (incoherent, paraxial)

Exit pupil diameter w . Distance to image z_i

$$P(x, y) = \text{circ}\left(\frac{r}{w/2}\right)$$

$$H(x, y) = \text{circ}\left(\frac{\lambda z_i f_r}{w/2}\right) \quad \text{Coherent transfer function}$$

$$f_c = \frac{w}{\lambda z_i} \quad \text{OTF cutoff frequency (w is exit pupil diameter)}$$

$$\Delta x \leq \frac{1}{2f_c} = \frac{1}{2} \frac{\lambda z_i}{w} \quad \text{Nyquist sampling detector spacing}$$

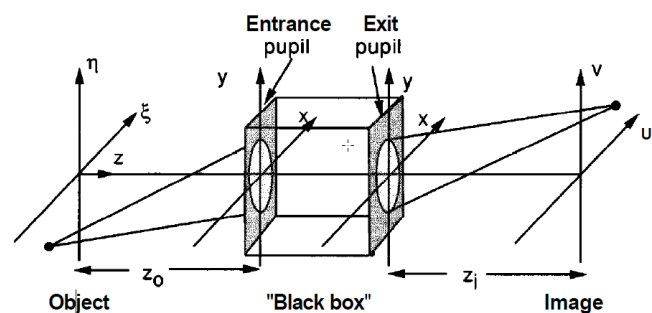
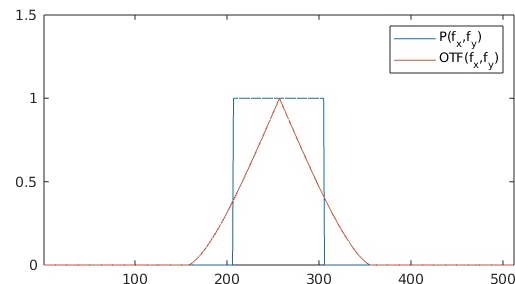
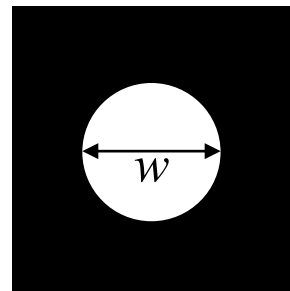


FIGURE 6.1
Generalized model of an imaging system.



Sampling for an imaging system (incoherent, non-paraxial)

Exit pupil diameter w . Distance to image z_i

$$\Delta x \leq \frac{1}{2f_c}$$

$$\Delta x \leq \frac{\lambda}{4NA_X}$$

$$\Delta x \leq \frac{M\lambda}{4NA_E}$$

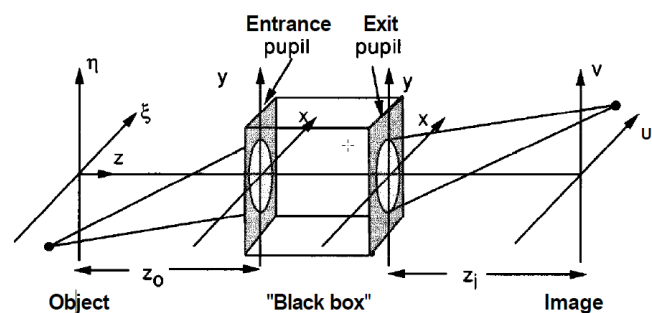
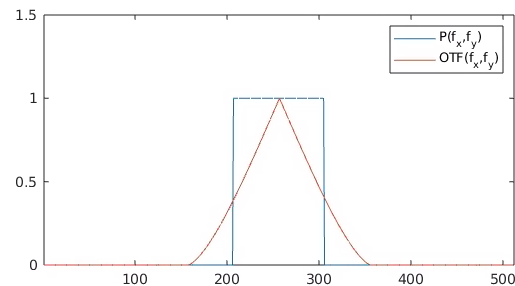
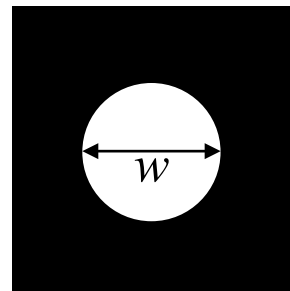
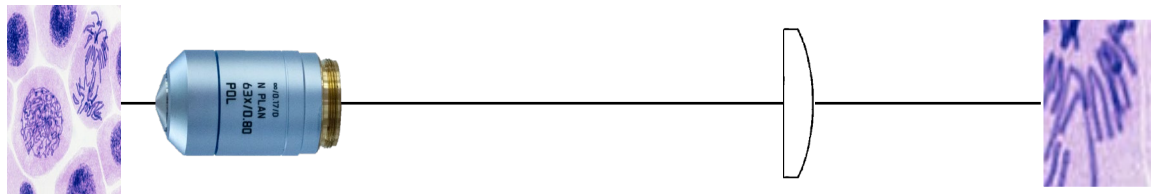
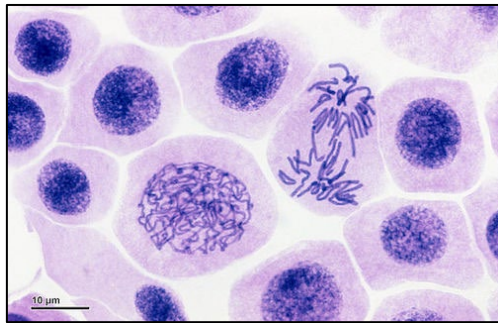


FIGURE 6.1
Generalized model of an imaging system.



An optical microscope

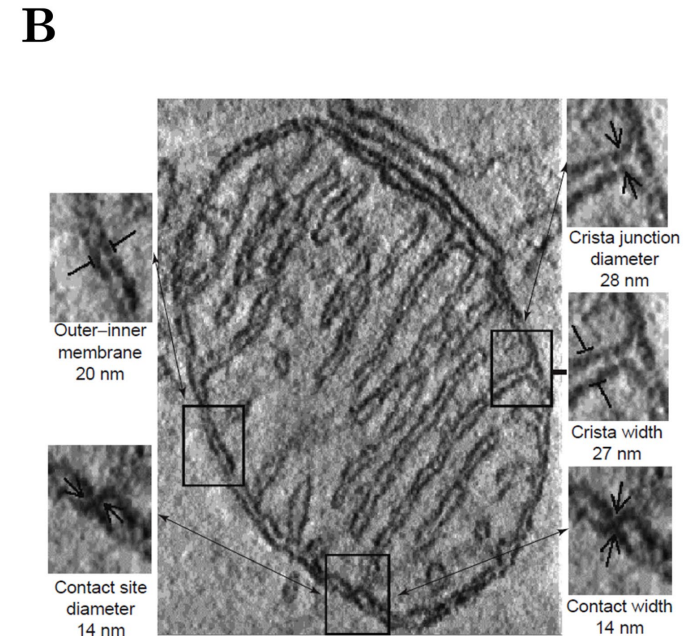
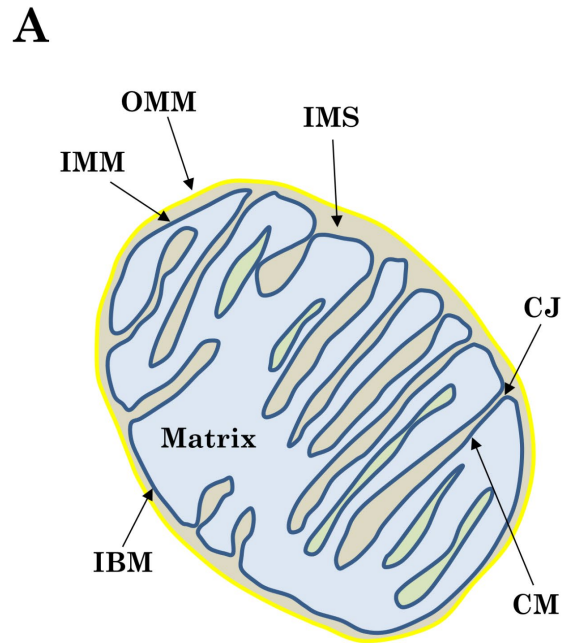
What NA do I need to resolve these DNA strains?



How small should my pixel size be to ensure no info is lost?

Mitochondria crista

What NA do I need to resolve them?



Discrete Fourier transform (DFT)

Discrete Fourier transform (DFT)

DFT “converts a finite sequence of equally-spaced samples of a function into a same-length sequence of equally-spaced samples of the **reciprocal-space** Fourier transform”

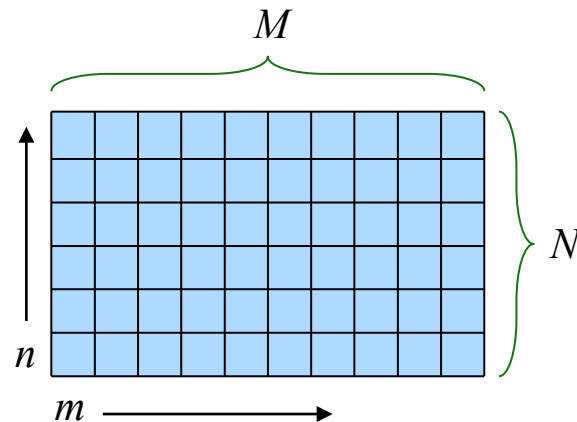
DFT is not an approximation of the FT

- Exact numerical transformation
- Orthogonal basis
- Unique, reversible
- Own set of theorems

Symmetric definition → Different than Goodman’s

$$G_{p,q} = \frac{1}{\sqrt{MN}} \sum_{m=0}^{M-1} \sum_{n=0}^{N-1} g_{m,n} \exp \left[-i2\pi \left(\frac{mp}{M} + \frac{nq}{N} \right) \right]$$

$$g_{m,n} = \frac{1}{\sqrt{MN}} \sum_{p=0}^{M-1} \sum_{q=0}^{N-1} G_{p,q} \exp \left[i2\pi \left(\frac{mp}{M} + \frac{nq}{N} \right) \right]$$



Example DFT theorems

Shift theorems in real and reciprocal space

$$\text{DFT} \{ g_{m-l,n} \} = G_{p,q} \exp \left[-i2\pi \frac{lp}{M} \right]$$

$$\text{DFT} \left\{ g_{m,n} \exp \left[i2\pi \frac{lm}{M} \right] \right\} = G_{p-l,q}$$

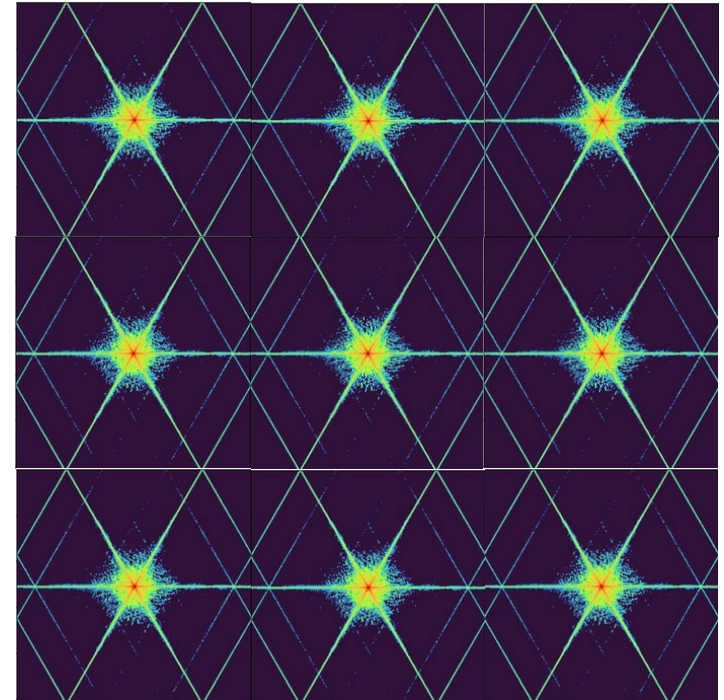
Periodic DFT

DFT views both the time and frequency domains as inherently periodic

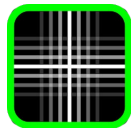
$$\text{DFT} \left\{ g_{m,n} \exp \left[i2\pi \frac{lm}{M} \right] \right\} = G_{p-l,q}$$

Notice that for a shift of M

$$G_{p-M,q} = \text{DFT} \left\{ g_{m,n} \exp \left[i2\pi \frac{lM}{M} \right] \right\} = \text{DFT} \{ g_{m,n} \} = G_{p,q}$$



Periodic DFT



DFT views both the time and frequency domains as inherently periodic

Notice that for a shift of M

$$G_{p-M,q} = \text{DFT} \left\{ g_{m,n} \exp \left[i2\pi \frac{lM}{M} \right] \right\} = \text{DFT} \{ g_{m,n} \} = G_{p,q}$$

DFT will see a “sharp”
edge here

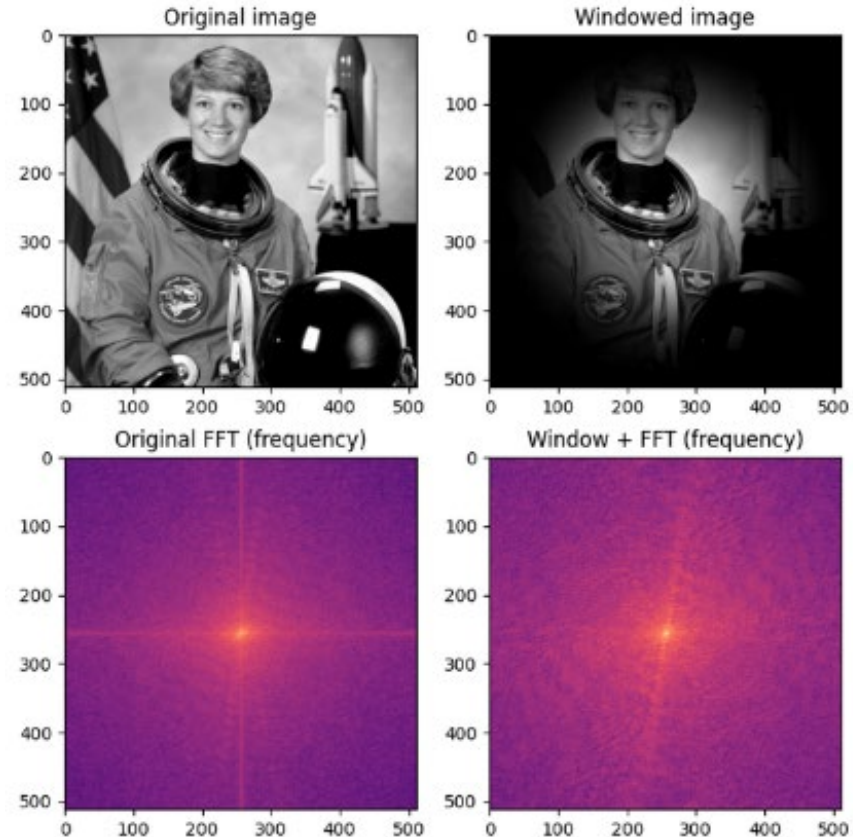


Apodization of edges



To reduce the edge effect, and get a good estimate of the frequencies really present in the image we should use image apodization

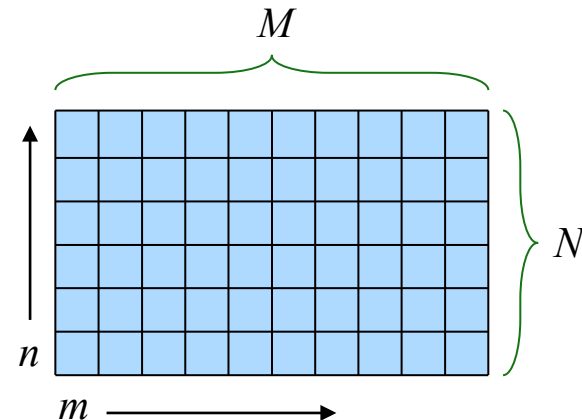
Here a Hanning window is used, but can also be a partial Hanning window.



Relation to the continuous FT

Often, we do want to use the DFT to approximate the FT
(notation and derivation different than Goodman's)

$$G(f_x, f_y) = \iint_{-\infty}^{\infty} g(x, y) \exp(-i2\pi [f_x x + f_y y]) dx dy$$



$$x = m\Delta x$$

$$y = n\Delta y$$

$$f_x = p\Delta f_x$$

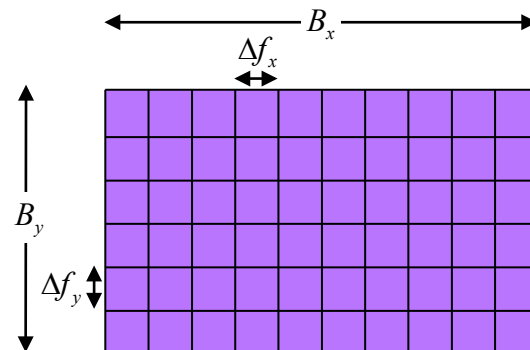
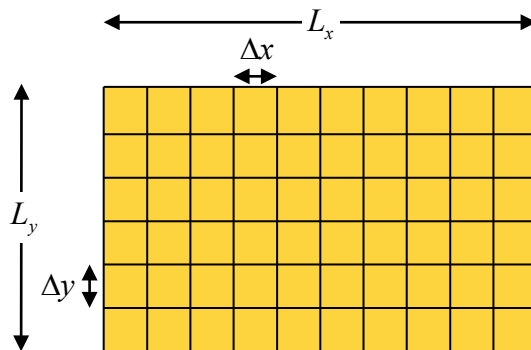
$$f_y = q\Delta f_y$$

$$L_x = M\Delta x$$

$$L_y = N\Delta y$$

$$B_x = M\Delta f_x$$

$$B_y = N\Delta f_y$$



Relation to the continuous FT



EPFL

$$G(f_x, f_y) = \int \int_{-\infty}^{\infty} g(x, y) \exp(-i2\pi [f_x x + f_y y]) dx dy$$

$$G(p\Delta f_x, q\Delta f_y) = \sum_{m=0}^{M-1} \sum_{n=0}^{N-1} g(m\Delta x, n\Delta y) \exp(-i2\pi [mp\Delta f_x \Delta x + nq\Delta f_y \Delta y]) \Delta x \Delta y$$

$$G(p\Delta f_x, q\Delta f_y) = \Delta x \Delta y \sqrt{MN} \frac{1}{\sqrt{MN}} \sum_{m=0}^{M-1} \sum_{n=0}^{N-1} g(m\Delta x, n\Delta y) \exp\left(-i2\pi \left[\frac{mp}{M} + \frac{nq}{N}\right]\right)$$

$$G_{p,q} = \frac{1}{\sqrt{MN}} \sum_{m=0}^{M-1} \sum_{n=0}^{N-1} g_{m,n} \exp\left[-i2\pi \left(\frac{mp}{M} + \frac{nq}{N}\right)\right]$$

$$x = m\Delta x$$

$$y = n\Delta y$$

$$f_x = p\Delta f_x$$

$$f_y = q\Delta f_y$$

$$\Delta x \Delta f_x = \frac{1}{M}$$

$$\Delta y \Delta f_y = \frac{1}{N}$$

Relation to the continuous FT



EPFL

$$G(f_x, f_y) = \iint_{-\infty}^{\infty} g(x, y) \exp(-i2\pi [f_x x + f_y y]) dx dy$$

$$G(p\Delta f_x, q\Delta f_y) = \Delta x \Delta y \sqrt{MN} \frac{1}{\sqrt{MN}} \sum_{m=0}^{M-1} \sum_{n=0}^{N-1} g(m\Delta x, n\Delta y) \exp\left(-i2\pi \left[\frac{mp}{M} + \frac{nq}{N}\right]\right)$$

$$G(p\Delta f_x, q\Delta f_y) = \Delta x \Delta y \sqrt{MN} \text{DFT} \{g(m\Delta x, n\Delta y)\}$$

$$x = m\Delta x$$

$$y = n\Delta y$$

$$f_x = p\Delta f_x$$

$$f_y = q\Delta f_y$$

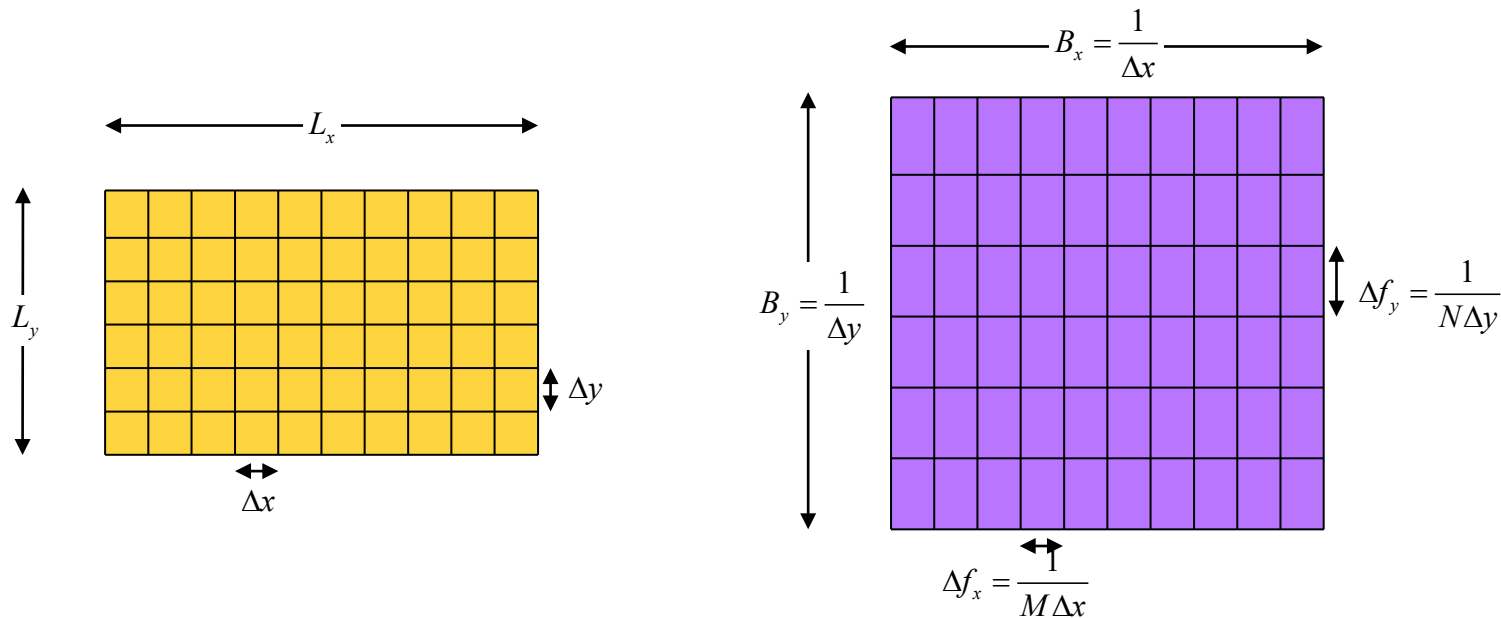
$$\Delta x \Delta f_x = \frac{1}{M}$$

$$\Delta y \Delta f_y = \frac{1}{N}$$

DFT on rectangular images

A very common mistake in filtering rectangular images with square pixels $M > N$

$$\begin{aligned}x &= m\Delta x & L_x &= M\Delta x \\y &= n\Delta y & L_y &= N\Delta y \\f_x &= p\Delta f_x & B_x &= M\Delta f_x \\f_y &= q\Delta f_y & B_y &= N\Delta f_y\end{aligned}$$



$$\begin{aligned}\Delta x \Delta f_x &= \frac{1}{M} \\ \Delta y \Delta f_y &= \frac{1}{N}\end{aligned}$$